

Leica Pegasus:Backpack

Mobile reality capture



Real estate property documentation

Enhanced trajectory calculation with SLAM technology for indoor mapping purposes makes updating 2D drawings easy while adding the further value of images and LiDAR together.

Indoor mapping

Unlimited data collection even in pedestrian-only urban areas. Accelerate the data collection in underground areas or even in GNSS-denied areas - just wear, scan and produce. Document heritage sites with limited access or aged undocumented underground utility infrastructures.

BIM authoritative documentation

Bring productivity for BIM documentation to the next level. Supervise the construction progressively with a time economical professional solution that combines flexibility and accuracy in a unique system. Capturing accurate data for modelling or documenting a renovation has never been easier.

Leica Pegasus:Backpack product specifications

Camera sensor

Number of cameras	5
CCD size	2046 x 2046
Pixel size	5.5 x 5.5 microns
Maximum frame rate	2 fps x camera, equal to 160 M pixels x second
Lens	6.0mm focal
Coverage	360° x 200°

Scanner

Type	Dual Velodyne VLP-16
FOV horizontal/vertical	270°/30° (±15°) per scanner
Channels	16
Acquisition	600,000 pts/sec
Frequency	10Hz
Range	Usable range: 50 m

Control unit

Multi-core industrial PC, low power consumption, 1 TB SSD hard disk with USB3 interface. Ethernet and wireless connections available. Service support available through remote interface.

Battery system performance

Typical operating time	4 hrs
Time to full charge	3 hrs
Batteries	2 or 4 batteries
Battery life time extension	Batteries are hot-swappable (no shut down needed)
DC output	14.8V
Amp hours	23.2 Ah
Weight	1.8 kg for 4 batteries

GNSS/IMU/SPAN sensor

Includes triple band – L-Band, SBAS, and QZSS for GPS, GLONASS, Galileo, and BeiDou constellations, single and dual antenna support.

Environmental

Operating temperature	0° C to +40° C, non-condensing
IP protection class	IP 52
Storage temperature	- 20° C to +50° C, non-condensing

Productivity

Data produced per project (compressed)	1 GB every minute of walking
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Accuracy

Relative accuracy	2 cm – 3 cm for outdoor and indoor
Absolute position accuracy outdoor	5 cm
Absolute position accuracy indoor (SLAM based without control points)	5 cm to 50cm for 10 minutes walking, minimum 3 loop closures or double passes conditions
A variety of factors can influence a trajectory accuracy negatively including:	
<ul style="list-style-type: none"> • Small rooms or hallways • A need to pivot while walking • Stairs and uneven pavement • Extremely smooth or blank surfaces • Surfaces too far from the scanners • Fast vertical movement - elevators are not supported 	

Under typical indoor conditions, the lower range of the accuracy specification can be achieved.

Images Point cloud

JPEG and ASCII for photogrammetric parameters
Binary LAS 1.2. X,Y,Z, intensity, RGB values
Colourisation by camera pictures
Hexagon Point Format
E57, 2D/3D DXF, PTS, DWG, DGN
NMEA, KMZ

Trajectory

Sensor platform

Frame material	Carbon fiber
Cover material	High resistance industrial textile
Weight	11.5 kg without batteries
Weight with case	32 kg including accessories
Size	73 x 27 x 31 cm
Size with case	95 x 53 x 43 cm



From left to right:
Case, prism, tablet device, sensor system,
4 batteries with charging dock, external converter

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