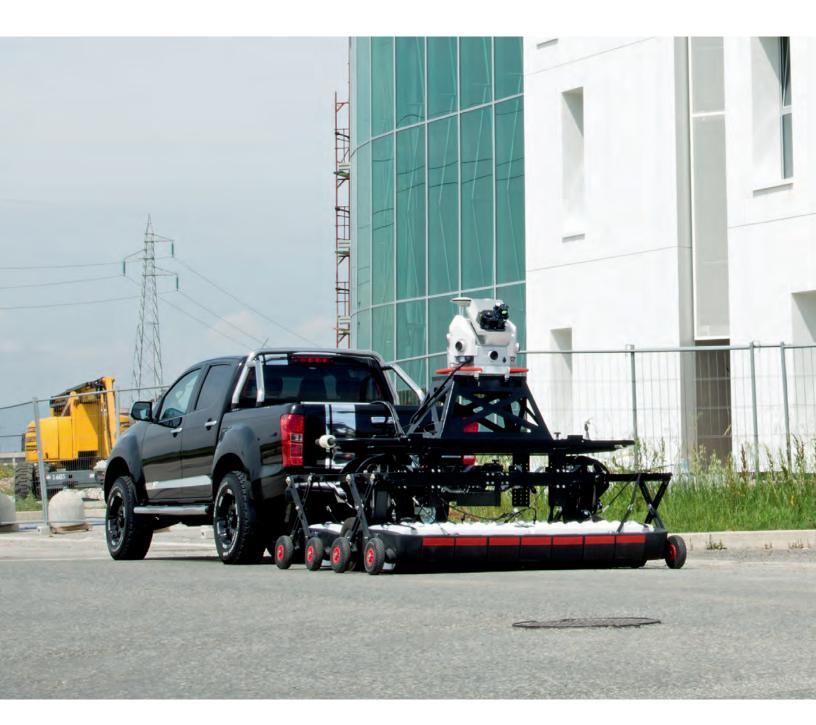
Leica Pegasus:Stream

Above and below ground mapping in a single integrated vehicle-towed solution









Leica Pegasus: Two Product Specifications

5.5 x 5.5 microns

(collected, compressed, stored)

8 fps x camera, equal to 256 M pixels x second

360° x 270° excluding rear down facing camera

8.0 mm focal, ruggedised; 2.7 mm focal, top

8 2000 x 2000

Camera Sensor

Number of cameras CCD size Pixel size Maximum frame rate

Lens Coverage

Scanner

Please refer to scanner manufacturer datasheet.

Control Unit

Multi-core industrial PC, low power consumption, 1TB SSD hard disk with USB3 interface. USB, Ethernet, and wireless connections available through the battery system. Service support available through remote interface.

Battery System Performance

Typical operating time 9 hrs, profiler version; 13 hrs, scanner version VAC input voltage 100 min to 240 max VAC autoranging AC input power (charge cycle) 350W Max AC input frequency 50/60 Hz Time to full charge 11.0 max h starting 0% DC output 21-29 volts . Watt/Amp hours 2685 Watts hours/104 Amp hours

GNSS/IMU/SPAN Sensor

Includes triple band – L-Band, SBAS, and QZSS for GPS, GLONASS, Galileo, and BeiDou constellations, single and dual antenna support, wheel sensor input, tactical grade no ITAR restrictions, low noise FOG IMU.

200 Hz

0.75

0.75

01

300

450

300

5

35,000 hour

Frequency MTBF Gyro bias in-run stability (±deg/hr) Gyro bias offset (deg/hr) Gyro angular rand. walk (deg/\/hr) Gvro scale factor (ppm) Gyro range (±deg/s) Accelerometer bias (mg) Accelerometer scale factor (ppm) Accelerometer range (±g) Position accuracy after 10 sec of outage duration

Sensor Platform

Weight Size

Size with case

Battery

Weight Size

Environmental

Operating temperature IP protection level

Storage temperature

Typical Accuracy*

Hortizontal accuracy Vertical accuracy Conditions

Productivity*

Data produced per project (compressed) Data produced after post processing (images and point cloud) 60 GB/h or 1.5 GB/km Post processing time

RMS heading. 51 kg (without case), 86 kg (with case)

0.020 m RMS horizontal, 0.020 m RMS vertical.

0.008 degrees RMS pitch/roll, 0.013 degrees

60 x 76 x 68 cm, profiler version 60 x 79 x 76 cm, Leica ScanStation P20 68 x 68 x 65 cm

34.8 kg 65 x 32 x 37cm

0°C to +40°C, non-condensing IP52, excluding the scanner. Please refer to scanner documentation. – 20°C to +50°C, non-condensing

0.020 m RMS 0.015 m RMS Without control points, open sky conditions

43 GB/h or 1.1 GB/km

1 hr of data collection equals 1 hr post-processing without colourising, 1 hr of data collection equals 5 hrs of post-processing with colourising.

Illustrations, descriptions and technical data are not binding. All rights reserved. Printed in Switzerland -Copyright Leica Geosystems AG, Heerbrugg, Switzerland, 2015. 836099en-us - 05.15 - INT

Leica Geosystems AG Heerbrugg, Switzerland

www.leica-geosystems.com http://di.leica-geosystems.com

Export Options Images

Point cloud

IPEG and ASCII for photogrammetric parameters Binary LAS 1.2. X,Y,Z, intensity, RGB values Colourisation by camera pictures Hexagon Point Format

1,000,000 points per second

No wheel sensor, no dual antenna

Accuracy Test Conditions*

Scanner frequency Image distance Driving speed System configuration Laser scanne Max baseline length

Repeatability*

Based on open sky, GPS+GLONASS processing, and phase differential. Points were measured manually from within the point cloud. A ring with 26 check points were collected 4 times, for a total of 104 observations. Check points were measured with TPS and levelling

3 m

40 km/h

ZF 9012

3.2 km

Resulting mean error for X,Y,Z was -0.004,-0.004,0.001 meters, and the resulting standard deviation for X,Y,Z was 0.011,0.012,0.008 meters.

* If not specified, datasheet is refers to a Leica Pegasus: Two with a ZF9012 profiler and an iMAR FSAS IMU. Datasheet is subject to change without notice.

228 kg (500 lbs)

18 kph (12mph)

87 scans/sec

72 W

IDS Stream EM Specifications

System Specifications

Overall weight (PC not included) Max. acquistion speed (@ std. Scan interval) Power consumption Positioning Number of control unit Scan rate per channel: (@512 samples/scan) Scan Interval Power Supply

Antenna Specifications

Environmental Antenna FootPrint Number of channels Antennas Central Frequencies Antenna Polarization Antenna spacing Certification

Accuracy

X,Y 7

Output formats Control

- Tomographic map view (c-Scan) including radar scan fusion

- 3D data visualization
- Advanced targeting using radarscan and tomographic view
- Layer picking for automatic analysis of sub-layers







IP65 1.84 m Width 38 200MHz (34 channels) and 600 MHz (4 channels)

Survey wheel and/or GPS or Total station

17 scans/m@200 MHz - 33 scan/m @ 600 MHz

3 synchronized DAD MCH FW

SLA Battery 12VDC 100 Ah

Leica Pegasus MDA control stop/start

Horizontal (HH) and Vertical (VV) 6 cm EC, FCC, IC

 ± 5 % of the depth (up to 1 m in depth)

SHP. DWG. DXF

±5 cm (up to 1 m in depth)

Software Specifications

Software Features GREG HD 3D CAD

- Radarscan viewer, filter and advanced filtering macros, multiple radar scan viewer